Dominik Winecki

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The Ohio State University

August 2021 - 2022

Pursuing an M.S. in Computer Science and Engineering

The Ohio State University

August 2018 - December 2021

Pursuing a Bachelor's in Computer Science and Engineering; 3.7 GPA

Experience

Azuga - Intern June 2021 – Present

- > Building, training, and deploying video AI models to find driving insights
- > Analyzing and enriching telematics data across sources

Mobikit - Engineering Intern

August 2019 – May 2021

- > Worked at a small telematics data startup for +70% of its existence prior to its acquisition by Azuga
- > Built realtime data ingest, processing, and analytics systems
- > Implemented a secure SQL query backend API, and frontend components that used it
- > Used AWS Lambda & Redshift for analytics scalability tests and demos up to 100 billion+ records
- > Wrote a spatio-temporal data reduction and transformation library; up to 200x faster querying of high-fidelity data.

READY Robotics - Software Engineering Intern

May 2019 – August 2019

- > Moved full product lineup to a unified custom network manager stack
- > Built auto-configuration tool for partner companies
- > Implemented service for cross-container and host configuration

OSU Interactive Data Systems Lab - Student Research Assistant

May 2018 - May 2019

- > Designed software for distributing video processing loads over a cluster in real time
- > Wrote "On the Fly Dynamic Graph Generation for Video Processing", presented at the 2019 National Conference of Undergraduate Research.
- > Built a HoloLens demo for querying by voice in Augmented Reality

Involvement

OHI/O Hackathon Org. - President, HackOHI/O 2020 & 2021 Co-lead

- > Co-lead Ohio's largest hackathon with 20+ organizers and 450+ participants
- > Worked on website, cross-org collaborations, and COVID-related migrations to online events

OSU Open Source Club - Webmaster \rightarrow VP \rightarrow President

> Gave talks on Rust and cloud hosting, rebuilt website, and managed server infrastructure

First Robotics Competition - Former Lead Programmer/Mentor, Team 1014

- > Developed a three degree-of-freedom vector based swerve drive control algorithm, which allows robots to rotate and move simultaneously
- > Spent a year working on a CNC Plasma cutter to allow for continuous rapid prototyping. Frame build time went from weeks to hours, weight halved, and strength increased

♥Skills

Languages: Python, C/C++, Java, Rust, SQL, AT_FX

Technology: Git, Linux, Docker/OCI Containers, Databases, AWS, Robot Operating System